

```
mouse:
1   mouse(jerry).
2   mouse(jerrys-nephew).

cat:
1   cat(tom).
2   cat(stumpy).

old:
1   old(jerry).
2   old(tom).

young:
1   young(jerrys-newpnew).
2   young(stumpy).

thing:
1   thing(X, jerry) :- cat(X).
2   thing(X, Y) :- mouse(X), cat(Y), young(X), young(Y).
```

at start

```
goal:
    thing(A, B).
backtrack possibilities
    none
```

step 1, unify with thing[1]

```
goal:
    {A=X, B=jerry} cat(X)
backtrack possibilities
    thing(A, B) [from rule 2]
```

step 2, unify with cat[1]

```
goal:
    {A=X, B=jerry, X=tom}
backtrack possibilities
    {A=X, B=jerry} cat(X) [from rule 2]
    thing(A, B) [from rule 2]
```

step 3, goal satisfied, print solution, backtrack

```
goal:
    {A=X, B=jerry} cat(X) [from rule 2]
backtrack possibilities
    thing(A, B) [from rule 2]
```

step 4, unify with cat[2]

```
goal:
    {A=X, B=jerry, X=stumpy}
backtrack possibilities
    thing(A, B) [from rule 2]
```

step 5, goal satisfied, print solution, backtrack

```
goal:
  thing(A, B) [at rule 2]
backtrack possibilities
  none
```

step 6, unify with thing[2]

```
goal:
  {A=X, B=Y} mouse(X), cat(Y), young(X), young(Y)
backtrack possibilities
  none
```

step 7, unify with mouse[1]

```
goal:
  {A=X, B=Y, X=jerry} cat(Y), young(X), young(Y)
backtrack possibilities
  {A=X, B=Y} mouse(X) [from rule 2], cat(Y), young(X), young(Y)
```

step 8, unify with cat[1]

```
goal:
  {A=X, B=Y, X=jerry, Y=tom} young(X), young(Y)
backtrack possibilities
  {A=X, B=Y, X=jerry} cat(Y) [from rule 2], young(X), young(Y)
  {A=X, B=Y} mouse(X) [from rule 2], cat(Y), young(X), young(Y)
```

step 9, attempt to unify with young[1] fail, young[2] fail; backtrack

```
goal:
  {A=X, B=Y, X=jerry} cat(Y) [from rule 2], young(X), young(Y)
backtrack possibilities
  {A=X, B=Y} mouse(X) [from rule 2], cat(Y), young(X), young(Y)
```

step 10, unify with cat[2]

```
goal:
  {A=X, B=Y, X=jerry, Y=stumpy} young(X), young(Y)
backtrack possibilities
  {A=X, B=Y} mouse(X) [from rule 2], cat(Y), young(X), young(Y)
```

step 11, attempt to unify with young[1] fail, young[2] fail; backtrack

```
goal:
  {A=X, B=Y} mouse(X) [from rule 2], cat(Y), young(X), young(Y)
backtrack possibilities
  none
```

step 12, unify with mouse[2]

```
goal:
  {A=X, B=Y, X=jerrys-nephew} cat(Y), young(X), young(Y)
backtrack possibilities
  none
```

step 13, unify with cat[1]

goal:

{A=X, B=Y, X=jerrys-nephew, Y=tom} young(X), young(Y)

backtrack possibilities

{A=X, B=Y, X=jerrys-nephew} cat(Y) [from rule 2], young(X), young(Y)

step 14, unify with young[1]

goal:

{A=X, B=Y, X=jerrys-nephew, Y=tom} young(Y)

backtrack possibilities

{A=X, B=Y, X=jerrys-nephew, Y=tom} young(X) [from rule 2], young(Y)

{A=X, B=Y, X=jerrys-nephew}, cat(Y) [from rule 2], young(X), young(Y)

step 15, attempt to unify with young[1] fail, young[2] fail; backtrack

goal:

{A=X, B=Y, X=jerrys-nephew, Y=tom} young(X) [from rule 2], young(Y)

backtrack possibilities

{A=X, B=Y, X=jerrys-nephew}, cat(Y) [from rule 2], young(X), young(Y)

step 16, attempt to unify with young[2], fail; backtrack

goal:

{A=X, B=Y, X=jerrys-nephew}, cat(Y) [from rule 2], young(X), young(Y)

backtrack possibilities

none

step 17, unify with cat[2]

goal:

{A=X, B=Y, X=jerrys-nephew, Y=stumpy} young(X), young(Y)

backtrack possibilities

none

step 19, unify with young[1]

goal:

{A=X, B=Y, X=jerrys-nephew, Y=stumpy} young(Y)

backtrack possibilities

{A=X, B=Y, X=jerrys-nephew, Y=stumpy} young(X) [from rule 2], young(Y)

step 20, attempt to unify with young[1] fail, young[2] succeed

goal:

{A=X, B=Y, X=jerrys-nephew, Y=stumpy}

backtrack possibilities

{A=X, B=Y, X=jerrys-nephew, Y=stumpy} young(X) [from rule 2], young(Y)

step 21, goal satisfied, print solution, backtrack

goal:

{A=X, B=Y, X=jerrys-nephew, Y=stumpy} young(X) [from rule 2], young(Y)

backtrack possibilities

none

step 19, unify with young[2]

goal:

{A=X, B=Y, X=jerrys-nephew, Y=stumpy} young(Y)

backtrack possibilities

none

step 20, unify with young[1] fail, young[2] succeed

goal:

{A=X, B=Y, X=jerrys-nephew, Y=stumpy}

backtrack possibilities

none

step 21, goal satisfied, print solution, backtrack

goal:

none

all done