<u>Deep Learning – Neural Nets</u>

The McCulloch-Pitts Perceptron, 1943

- "Perception" and "Electronic"
- A very simplified model of how a real neuron works
- "Perceptron" and "Neuron" used almost interchangably, but Perceptron is a little bit old fashioned now
- Any number of inputs, ai Sometimes on/off, sometimes continuous
- Each input has an associated weight, w_i Changing the weights is how it learns
- Output or State computed from weighted inputs $\sum a_i {}^{\times} w_i$
- But a non-linear Activation Function is applied to that sum $f(\sum a_i \times w_i)$
- Could be (but usually isn't) a cut-off function
 f(x) = if x < k then 0 else 1
 - each perceptron can have its own value for k
 - Or the Sigmoid (or Logistic) function, popular
 - $f(\mathbf{x}) = 1 / (1 + e^{-\mathbf{x}})$
 - easy to differentiate, that will turn out to be useful
- Or the Rectified Linear Unit (ReLU) function
 f(x) = max(0, x)
- Or the Softplus function, a continuous approximation to ReLU
 f(x) = log_e(1 + e^x)
- Or the Hyperbolic Tangent function tanh
 - $f(\mathbf{x}) = (e^{2\mathbf{x}} 1) / (e^{2\mathbf{x}} + 1)$
 - but that gives a range of -1 to +1
- There can also be a Bias
 - Typically a constant value -1 or +1
 - that is treated as an extra input with its own weight it can shift the curve given by f to the left or right

Layers

- One perceptron recognizes a straight-line/plane/hyperplane Separating one set of possible inputs from the other
- Originally arranged in a single layer Usually all receiving the same inputs from sensors And all recognizing different Features
- But that can't recognize such a simple thing as exclusive or
- Now usually arranged in multiple layers

This is what Deep Learning refers to There is an input layer and an output layer, any others are called Hidden Layers

• Just two layers can compute any continuous function As close as you like, just add more perceptrons

- Maybe softmax for final outputs when classifying e^{thisoutput} / ∑ e^{alloutputs} Suppose the actual outputs are 0.3, -0.4, 1.2, 0.2 the softmaxes are 0.21, 0.10, 0.51, 0.19 can use as probabilities, biggest tends to get exaggerated
- Big things, vision, language, etc. can use many layers
- Neurons in real brains are not really arranged in layers And are definitely not Fully Connected either

Training with only two layers, inputs and outputs

- Improve performance by adjusting weights throughout the network
- Diminishing Returns stop when it isn't making much difference any more
- Use a training set of course large set of pairs (inputs, desired outputs)
- adjust each link according to the amount of error it was responsible for
- For each training point, work out the Local Error of the entire network Just the difference between the actual output and the correct output squared of course, negative errors are just as bad as positive ones If there are multiple outputs, just average all their errors That is Mean Squared Error, MSE Sometimes Root Mean Square, RMS, is used instead
- Repeat that for the entire training set, averaging all the errors
- Repeat that for the entire training set, avIf that average error is small enough
 - the network has Converged. Training is over.