Decision Trees

Improving components of an agent by machine learning

- The components include
 - Converting from state conditions to actions Inferring information on the state from percepts Knowledge of what effects actions have Knowledge of the desirability of states etc
- Assume no prior knowledge, everything has to be learned
- Induction: from observations develop a general rule can be wrong
- Not deduction which can't be wrong
- The aim is to discover a function that
 - maps inputs (percepts of the state of the world) to an output: a fact that we would like to know, or an action we should take, or similar
- If the output is discrete, this is Classification
- If the output is continuous, it is called Regression

Supervised learning

- Provided with samples of inputs pictures perhaps
- Together with correct Labels or classifications for them such as "kitten", "puppy", "stop sign"
- The Training Set
- Discover a function that will correctly map inputs that have not been seen before to their correct labels or classifications

Unsupervised learning

- Given many samples of inputs
- Maybe detects Clusters: subsets of the inputs that share features
- Perhaps from many images it may notice a cluster that happens to be cats but it would not know that they are cats, just that there is this unnamed phenomenon in the world

Reinforcement learning

- A bit like the way babies learn
- Start off acting almost at random
- Receive awards or punishments based on the effects of those actions
- Learn which actions are most responsible

Back to supervised learning

- Given a training set of input-output pairs
 - $(x_1, y_1), (x_2, y_2), (x_3, y_3), (x_4, y_4), \dots, (x_N, y_N)$
- they actually come from some unknown function $y_i = f(x_i)$
- Try to discover another function, h, that approximates f.

- That function, h, is called a Hypothesis about the world
- Or a Model of the data
- Underfitting: h does not match the data properly
- Overfitting: h is too specifically fitted to the training data
 - It gets the test inputs right, but not new real-world inputs
 - e.g. for any 12-point numeric data set,
 - you can always find an 11th order polynomial that fits perfectly but it will have wild swings in it
 - A simple straight line might not fit the training set so well but do a better job in the real world - less noise

Big example: Should you wait for a table at a restaurant?

- The result of this function is just yes or no.
- The inputs come from 10 discrete percepts:

Alternate: is there an alternative near-by? Bar: is there a nice bar you could wait in? FriSat: true on Fridays and Saturdays Hungry: are we really hungry now? Patrons: none, some, or full. Price: cheap, middling, expensive

Raining: is it raining?

Reservation: have we got a reservation?

Type: french, italian, thai, burger

Time: greeter's estimate of the wait time: 0-10, 10-30, 30-60, >60 Training set is observed results of a person's actual decisions:

		Training set is observed results of a person s actual decisions.										
	Alt	Bar	FS	Hung	Patr	Price	Rain	Res	Туре	Time	Output	
1	yes	no	no	yes	some	exp	no	yes	fre	0-10	yes	
2	yes	no	no	yes	full	che	no	no	thai	30-60	no	
3	no	yes	no	no	some	che	no	no	bur	0-10	yes	
4	yes	no	yes	yes	full	che	yes	no	thai	10-30	yes	
5	yes	no	yes	no	full	exp	no	yes	fre	>60	no	
6	no	yes	no	yes	some	mid	yes	yes	ital	0-10	yes	
7	no	yes	no	no	none	che	yes	no	bur	0-10	no	
8	no	no	no	yes	some	mid	yes	yes	thai	0-10	yes	
9	no	yes	yes	no	full	che	yes	no	bur	>60	no	
10	yes	yes	yes	yes	full	exp	no	yes	ital	10-30	no	
11	no	no	no	no	none	che	no	no	thai	0-10	no	
12	yes	yes	yes	yes	full	che	no	no	bur	30-60	yes	

Decision trees

- (example diagram: Patr, Time, Alt, Hung, Res, Fri, Alt, Bar, Rain)
- Sometimes an expert can just give you a decision tree But experts in one field are not necessarily experts in logic A Knowledge Engineer has to conduct Knowledge Elicitation But either way, machine learning is not involved here
- A particular sub-kind of supervised learning

You get all the data all at once

Taking into account new training items can be expensive

• Some alternatives:

Type first would be bad

But Patrons first does much better

- Learning Curve: num of training examples vs proportion correct
- How do you learn the tree from the training set?
- A seemingly simple method

All remaining examples yes (or all no), then done.

Some yes and some no: find best attribute to split them and continue with the split sets of examples

No examples left: incomplete information

This combination of attrs has never been observed Pick parent's most common output value

Some examples but no attrs left:

These examples have same descrs but different labels Error or Noise in the data, nondeterministic, or unobservable

• But the second possibility leaves a lot unsaid. How do we find the best?

Entropy

- From Information Theory, not chemistry, sort of similar
- A measure of uncertainty
- Always called H
- Measured in bits
- Variable has only one possible value, a very very unfair coin? Entropy is zero - no uncertainty

You learn nothing from seeing the actual result

- Two equally likely values, a fair coin
 - From the result you learn yes or no Entropy is one bit
- Sixteen equally likely possibilities Four bits of entropy
- Two unequal possibilities, e.g. P(heads) = 0.99 and P(Tails) = 0.01 There is less uncertainty
 - You learn less from seeing the actual result
 - If you just guessed you would almost always be right So the entropy should be very small
- For a variable V with possible values v₁, v₂, v₃, v₄, ...
 - $H(V) = \Sigma P(v_i) \times \log_2(1 / P(v_i))$
 - = $\Sigma P(v_i) \times \log_2(P(v_i))$
- The fair coin
 - $H(Toss) = -(0.5 \times \log_2 0.5 + 0.5 \times \log_2 0.5) = 1.0$
- The very unfair coin

 $H(Toss) = -(0.99 \times \log_2 0.99 + 0.01 \times \log_2 0.01) = 0.08$

- Define B(p), entropy of a boolean variable V with P(true) = p B(V) = - (p×log₂p + (1-p)×log₂(1-p))
- A training set with Y yes results and N no results H(Output) = B(Y / (Y + N))
- The result of a test (e.g. what is the value of Price?) gives us some information

so it reduces our uncertainty of the overall output so it reduces the entropy Going with the example table, call the training examples $E_1, E_2, ..., E_{12}$ Initially our set of examples is all of them, $S = \{E_1, E_2, ..., E_{12}\}$ If all examples have the same outcome, then all done P = number of times in S that result is yes = 6 N = number of times it is false = 6For each of the possible attributes A (Alternate, Bar, etc) For each possible value of that attribute V (yes, no, etc) P_V = number of examples where A has value V and outcome is yes N_V = number of examples where A has value V and outcome is no so $P_V + N_V$ is the number of times A has value V and P + N is the total number of examples $P_{A,V} = (P_V + N_V) / (P + N)$ is the probability that A has value V $P_V / (P_V + N_V)$ is the prob that A being V leads to yes outcome so $B(P_V / (P_V + N_V))$ is entropy left after finding that A equals V so $P_{A,V} \times$ that is entropy in a particular case weighted by probability of that case happening Add up all those weighted entropies to find the total entropy that would remain after discovering the value of A The entropy we had before all of this was B(P / (N + P))so the entropy lost (therefore information gained) by asking the question A is that original entropy minus the sum Pick the attribute that gave the highest information gain Let's say that attribute has possible values $V_1, V_2, ..., V_N$, Split S into subsets of the examples $S_1, S_2, ..., S_N$, where S_i is the subset of examples where the chosen attribute equals V_i Analyse each of those subsets in exactly the same way. In practice So the *expected* entropy remaining after testing A is Remainder(A) = Σ ((P_V + N_V) / (P + N)) × B(P_V / (P_V+N_V)) The Information Gain is the loss in entropy Gain(A) = B(Y / (Y + N)) - Remainder(A)Example: Gain(Patrons) = 1 - ((2/12)B(0/2) + (4/12)B(4/4) + (6/12)B(2/6))= 0.541Example: Gain(Type) = 1 - ((2/12)B(1/2) + (2/12)B(1/2) + (4/12)B(2/4) + (4/12)B(2/4))= () The Best attribute to test when building a decision tree is the one with the highest information gain. Possible problems with decision trees

• Might overfit

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- Might make irrelevant tests, making it unnecessarily big
- Pruning remove irrelevant tests Statistical methods Beyond us.
- Continuous attributes (Price, Time, etc)

Discretise - like we did Split Point test - e.g. Time > 27

- Not continuous but still too many values (e.g. Zip code) Information Gain Ratio - Beyond us
- Continuous output value
 - Regression Tree
 - Decisions based on linear function of some attributes
- What if two training set examples are contradictory?