More Complex Search Methods

Local search

- Don't care about paths just want the successful final state e.g. 8 Queens: only the solution matters
- Don't record paths to states
- Don't even record the set of states that have been reached
- Saves a lot of memory
- Not systematic: may never find some states
- May re-explore some states
- But often finds a good enough solution in an infinite state space

Maybe rather than a global best, we can accept a local best

• Hill climbing

Objective function

Steepest ascent

Eight Queens again

Initial state random, one per row

Heuristic = number of queens under attack

Greedy local search

Unlikely to find global maximum

Random restarts

Simulates annealing, two styles

Test random moves, take first that gives an improvement After finding solution, knock the system about a bit.

- Random walks
- Local beam search

Start with N random start states Generate all successor states Only keep the best N of them

• Evolutionary or Genetic algorithms

e.g. 8 Queens again

8 digit strings, digit = column for each row Many other examples of uses

Non-deterministic actions

Actuator may fail, or real world may intervene

Can't be sure of successor state for each action

e.g. powerful but erratic vacuum cleaner, 8 states

And-or trees

Or node for each action having different possible outcomes And node because all possible outcomes must be solved Not really a tree, may have loops

Partially observable environment

• Totally Sensorless

Assembly line, sequence of moves will result in correct position Broad spectrum antibiotic instead of blood test first Sensorless but reliable vacuum cleaner

Start state could be anything, 8 possible

Each action reduces set of possible states (if it works)

Don't always know which actions are legal

Maybe illegal actions have no effect

State spaces can be huge, 2^N instead of N Sometimes impossible, e.g. 8 puzzle

- Partially broken robot trying to find where it is in a known maze Percepts are four bits - is there a block in each direction?
- Partially sensorless 15-puzzle with sensor only in top left corner

On-line search

- Off-line means you can work out a solution before doing anything
- On-line, you need to decide after actually making a move e.g. robot mapping an unknown maze
 - Can not determine possible actions without actually being there
- Dead ends (not as in a maze), states from which nothing can be done Some actions may be irreversible Some state spaces are not safely explorable