## Intelligent Agents

Robots?

Sensors and actuators.

What is rational? Depends on:

- Percept sequence
- Actions that can be taken
- Prior knowledge
- Performance measure how to identify success
- Learning? Along the way, or from previous runs

## Examples

- Automatic vacuum cleaner
- Self-driving car
- Chess player
- Speech understander

Task environment

- Sensors
- Actuators
- Environment
  - Fully or partially observable? Deterministic or non-deterministic? Episodic or sequential? Static or dynamic?
- Performance measure

Agent programs

- Maps percept sequences to actions Big table? Chess 10<sup>150</sup> Small program - logarithm tables - the whole point of programming
- Learning?
- Different styles:
  - Reflex current percept only Model based - keep track of unobservable parts
  - Goal based current state is not enough
  - Utility faster / more efficiently but isn't that a goal?

## **Rational Agents**

- What is rational at any point in time?
- Depends on:
  - Prior knowledge of environment Percept sequence up to now Actions that can be performed Performance measure
- For each possible percept sequence,

Should take the action that is expected to maximise performance measure given the evidence and knowledge provided
Rationality is not perfection